

LAMPIRAN

Lampiran 1. Pengecekan Turnitin

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Lampiran 2. Kode Program Blynk

```
#define BLYNK_TEMPLATE_ID "TMPL6SnUsbCM5"

#define BLYNK_TEMPLATE_NAME "Microgreen"

#include <WiFi.h>

#include <EEPROM.h>

#include "GravityTDS.h"

#include <DHT.h>

#include "BlynkSimpleEsp32.h"

// WiFi & Blynk
char auth[] = "XPaBUS-eh3FuTCh3_myngs2vBIT7O5w-";
char ssid[] = "Dimas Home";
char pass[] = "DD772233";

// Pin Sensor & Relay
#define TDS_SENSOR_PIN 35
#define DHT_PIN 23
#define DHT_TYPE DHT22
#define SOIL_PIN 34

#define RELAY1_PIN 5
#define RELAY2_PIN 26
#define RELAY3_PIN 27
#define RELAY4_PIN 15

#define EEPROM_SIZE 512
```

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// RS485 NPK Sensor (Modbus RTU)

#define RE_DE_PIN 4

#define RXD2 16

#define TXD2 17

// Flowmeter YF-S401

#define FLOW_AIR_PIN 18

#define FLOW_ABMIX_PIN 19

#define PULSES_PER_LITER 450

const float FLOW_FACTOR = 7.5; // datasheet

// Pulse counters, rates, process status
volatile unsigned long flowAirPulseCount = 0;
volatile unsigned long flowABMixPulseCount = 0;
portMUX_TYPE flowMux = portMUX_INITIALIZER_UNLOCKED;
float flowAirRate = 0.0, flowABMixRate = 0.0;
unsigned long lastFlowMillis = 0;

// Dosing state
bool airProcessActive = false;
bool abMixProcessActive = false;
unsigned long airPulseStart = 0, abMixPulseStart = 0;

// Modbus NPK sensor

const byte nitro[] = {0x01, 0x03, 0x00, 0x04, 0x00, 0x01, 0x60,
0x0B};

const byte phos[] = {0x01, 0x03, 0x00, 0x05, 0x00, 0x01, 0xB1,
0xCB};

```

```

const byte pota[] = {0x01, 0x03, 0x00, 0x06, 0x00, 0x01, 0x61,
0xCA};

// Sensor objects
DHT dht(DHT_PIN, DHT_TYPE);
GravityTDS gravityTds;
BlynkTimer timer;

// Sensor variables
float tdsValue = 0, temperature = 25, humidity = 0;
int soilValue = 0, soilPercent = 0;
uint16_t valN = 0, valP = 0, valK = 0;

// Success counters
unsigned long countDHT_ok = 0, countTDS_ok = 0, countSoil_ok = 0,
countNPK_ok = 0;

// Interrupt handlers
void IRAM_ATTR countFlowAir() { portENTER_CRITICAL_ISR(&flowMux);
if (airProcessActive) flowAirPulseCount++;
portEXIT_CRITICAL_ISR(&flowMux);}

void IRAM_ATTR countFlowABMix() {
portENTER_CRITICAL_ISR(&flowMux); if (abMixProcessActive)
flowABMixPulseCount++; portEXIT_CRITICAL_ISR(&flowMux);}

// Read NPK sensor via RS485
uint16_t readNPK(const byte* frame, const char* label) {
    byte response[16]; byte index = 0;
    digitalWrite(RE_DE_PIN, HIGH); delay(2);
    Serial2.write(frame, 8); Serial2.flush(); delay(2);
    digitalWrite(RE_DE_PIN, LOW);

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    unsigned long start = millis();

    while (Serial2.available() < 7 && millis() - start < 500);

    while (Serial2.available() && index < 7) { response[index++] =
Serial2.read(); }

    Serial.print(label); Serial.print(" HEX: ");

    for (byte i = 0; i < index; i++) Serial.printf("%02X ",
response[i]);

    Serial.println();

    if (index == 7) return (response[3] << 8) | response[4];

    Serial.print(label); Serial.println(" Gagal baca."); return 0;
}

// Setup
void setup() {
    Serial.begin(115200); EEPROM.begin(EEPROM_SIZE);
    pinMode(RELAY1_PIN, OUTPUT); pinMode(RELAY2_PIN, OUTPUT);
    pinMode(RELAY3_PIN, OUTPUT); pinMode(RELAY4_PIN, OUTPUT);
    digitalWrite(RELAY1_PIN, HIGH); digitalWrite(RELAY2_PIN, HIGH);
    digitalWrite(RELAY3_PIN, HIGH); digitalWrite(RELAY4_PIN, HIGH);
    dht.begin();

    gravityTds.setPin(TDS_SENSOR_PIN); gravityTds.setAref(3.3);
gravityTds.setAdcRange(4096); gravityTds.begin();

    WiFi.begin(ssid, pass); Blynk.begin(auth, ssid, pass);

    pinMode(RE_DE_PIN, OUTPUT); digitalWrite(RE_DE_PIN, LOW);

    Serial2.begin(4800, SERIAL_8N1, RXD2, TXD2);

    pinMode(FLOW_AIR_PIN, INPUT_PULLUP); pinMode(FLOW_AB MIX_PIN,
INPUT_PULLUP);

    attachInterrupt(digitalPinToInterrupt(FLOW_AIR_PIN),
countFlowAir, RISING);

    attachInterrupt(digitalPinToInterrupt(FLOW_AB MIX_PIN),
countFlowABMix, RISING);
}

```

```

    timer.setInterval(2000L, sendAllSensorData);
}

// Send all sensor data to Blynk
void sendAllSensorData() {
    temperature = dht.readTemperature();
    humidity = dht.readHumidity();
    if (!isnan(temperature) && !isnan(humidity)) countDHT_ok++;
    if (isnan(temperature)) temperature = 25.0;

    gravityTds.setTemperature(temperature);
    gravityTds.update();
    tdsValue = gravityTds.getTdsValue();
    if (tdsValue > 0 && tdsValue < 3000) countTDS_ok++;

    soilValue = analogRead(SOIL_PIN);
    soilPercent = map(soilValue, 4095, 0, 0, 100);
    soilPercent = constrain(soilPercent, 0, 100);
    if (soilPercent >= 0 && soilPercent <= 100) countSoil_ok++;

    valN = readNPK(nitro, "Nitrogen"); delay(200);
    valP = readNPK(phos, "Phosphorous"); delay(200);
    valK = readNPK(pota, "Potassium"); delay(200);
    if (valN > 0 && valP > 0 && valK > 0) countNPK_ok++;

    unsigned long now = millis();
    if (now - lastFlowMillis >= 1000) {
        unsigned long airCount, abCount;

```

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portENTER_CRITICAL(&flowMux);

airCount = flowAirPulseCount;

abCount = flowABMixPulseCount;

flowAirPulseCount = 0;

flowABMixPulseCount = 0;

portEXIT_CRITICAL(&flowMux);

float airHz = airCount / 1.0, abHz = abCount / 1.0;

flowAirRate = airHz / FLOW_FACTOR;

flowABMixRate = abHz / FLOW_FACTOR;

lastFlowMillis = now;

Serial.printf("Flow Air: %.2f L/min, Flow AB Mix: %.2f
L/min\n", flowAirRate, flowABMixRate);

Blynk.virtualWrite(V11, flowAirRate);
Blynk.virtualWrite(V12, flowABMixRate);
}

// 100ml dosing, with interrupt safety
if (airProcessActive) {

    unsigned long pulses;

    portENTER_CRITICAL(&flowMux);

    pulses = flowAirPulseCount - airPulseStart;

    portEXIT_CRITICAL(&flowMux);

    float airMl = (float)pulses / PULSES_PER_LITER * 1000.0;

    if (airMl >= 100.0) {

        digitalWrite(RELAY3_PIN, HIGH);

        airProcessActive = false;
    }
}

```

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        Blynk.virtualWrite(V20, 0);
    }
}

if (abMixProcessActive) {
    unsigned long pulses;

    portENTER_CRITICAL(&flowMux);

    pulses = flowABMixPulseCount - abMixPulseStart;

    portEXIT_CRITICAL(&flowMux);

    float abMl = (float)pulses / PULSES_PER_LITER * 1000.0;
    if (abMl >= 100.0) {
        digitalWrite(RELAY4_PIN, HIGH);
        abMixProcessActive = false;
        Blynk.virtualWrite(V21, 0);
    }
}

Serial.printf("Suhu: %.1f°C | Kelembapan: %.1f%% | TDS: %.0f ppm
| Soil: %d%% | N: %d | P: %d | K: %d\n",
    temperature, humidity, tdsValue, soilPercent, valN, valP,
    valK);

Serial.printf("Pembacaan BERHASIL: DHT=%lu, TDS=%lu, Soil=%lu,
NPK=%lu\n",
    countDHT_ok, countTDS_ok, countSoil_ok, countNPK_ok);

Blynk.virtualWrite(V25, countDHT_ok);
Blynk.virtualWrite(V26, countTDS_ok);
Blynk.virtualWrite(V27, countSoil_ok);
Blynk.virtualWrite(V28, countNPK_ok);
Blynk.virtualWrite(V4, temperature);

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    Blynk.virtualWrite(V5, humidity);
    Blynk.virtualWrite(V6, tdsValue);
    Blynk.virtualWrite(V7, soilPercent);
    Blynk.virtualWrite(V8, valN);
    Blynk.virtualWrite(V9, valP);
    Blynk.virtualWrite(V10, valK);
}

// Relay control via Blynk
BLYNK_WRITE(V0) { digitalWrite(RELAY1_PIN, !param.asInt()); }
BLYNK_WRITE(V1) { digitalWrite(RELAY2_PIN, !param.asInt()); }
BLYNK_WRITE(V2) { digitalWrite(RELAY3_PIN, !param.asInt()); }
BLYNK_WRITE(V3) { digitalWrite(RELAY4_PIN, !param.asInt()); }

// Button V20: Dosing air 100ml
BLYNK_WRITE(V20) {
    if (param.asInt() == 1 && !airProcessActive) {
        airProcessActive = true;
        portENTER_CRITICAL(&flowMux);
        airPulseStart = flowAirPulseCount;
        portEXIT_CRITICAL(&flowMux);
        digitalWrite(RELAY3_PIN, LOW);
    }
}

// Button V21: Dosing AB mix 100ml
BLYNK_WRITE(V21) {
    if (param.asInt() == 1 && !abMixProcessActive) {
        abMixProcessActive = true;
    }
}

```

```
portENTER_CRITICAL(&flowMux);  
abMixPulseStart = flowABMixPulseCount;  
portEXIT_CRITICAL(&flowMux);  
digitalWrite(RELAY4_PIN, LOW);  
}  
}  
  
void loop() {  
  Blynk.run();  
  timer.run();  
}
```

